

ALWAYS LEARNING PEARSON



HUGHES ELECTRICAL & ELECTRONIC TECHNOLOGY



PEARSON

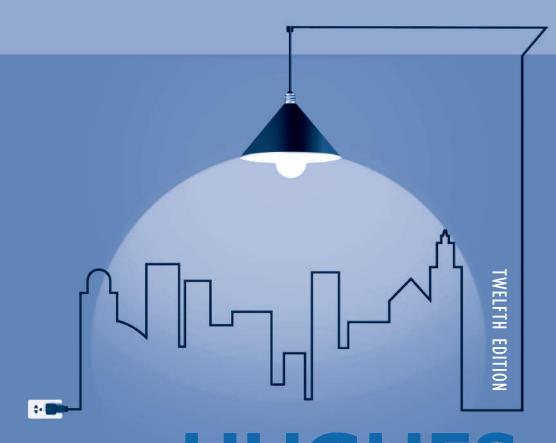
At Pearson, we have a simple mission: to help people make more of their lives through learning.

We combine innovative learning technology with trusted content and educational expertise to provide engaging and effective learning experiences that serve people wherever and whenever they are learning.

From classroom to boardroom, our curriculum materials, digital learning tools and testing programmes help to educate millions of people worldwide – more than any other private enterprise.

Every day our work helps learning flourish, and wherever learning flourishes, so do people.

To learn more, please visit us at www.pearson.com/uk



HUGHES ELECTRICAL & ELECTRONIC TECHNOLOGY

EDWARD HUGHES

REVISED BY JOHN HILEY, KEITH BROWN & IAN McKENZIE SMITH

PEARSON

Pearson Education Limited

Edinburgh Gate Harlow CM20 2JE United Kingdom Tel: +44 (0)1279 623623

Web: www.pearson.com/uk

First published under the Longman imprint 1960 Twelfth edition published 2016 (print and electronic)

- © Pearson Education Limited 1960, 2012 (print)
- © Pearson Education Limited 2016 (print and electronic)

The print publication is protected by copyright. Prior to any prohibited reproduction, storage in a retrieval system, distribution or transmission in any form or by any means, electronic, mechanical, recording or otherwise, permission should be obtained from the publisher or, where applicable, a licence permitting restricted copying in the United Kingdom should be obtained from the Copyright Licensing Agency Ltd, Bernard's Inn, 86 Fetter Lane, London EC4A 1EN.

The ePublication is protected by copyright and must not be copied, reproduced, transferred, distributed, leased, licensed or publicly performed or used in any way except as specifically permitted in writing by the publishers, as allowed under the terms and conditions under which it was purchased, or as strictly permitted by applicable copyright law. Any unauthorised distribution or use of this text may be a direct infringement of the authors' and the publisher's rights and those responsible may be liable in law accordingly.

All trademarks used herein are the property of their respective owners. The use of any trademark in this text does not vest in the author or publisher any trademark ownership rights in such trademarks, nor does the use of such trademarks imply any affiliation with or endorsement of this book by such owners.

Contains public sector information licensed under the Open Government Licence (OGL) v3.0. http://www.national-archives.gov.uk/doc/open-government-licence/version/3/.

The screenshots in this book are reprinted by permission of Microsoft Corporation.

Pearson Education is not responsible for the content of third-party internet sites.

ISBN: 978-1-292-09304-8 (print) 978-1-292-09308-6 (PDF) 978-1-292-13459-8 (ePub)

British Library Cataloguing-in-Publication Data

A catalogue record for the print edition is available from the British Library

Library of Congress Cataloging-in-Publication Data

A catalog record for the print edition is available from the Library of Congress

10 9 8 7 6 5 4 3 2 1 20 19 18 17 16

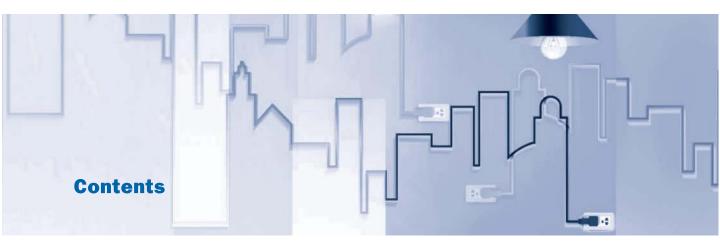
Cover image: My Life Graphic/Shutterstock

Print edition typeset in 10/11pt Ehrhardt MT Pro by Lumina Datamatics Print edition printed in Slovakia by Neografia

NOTE THAT ANY PAGE CROSS REFERENCES REFER TO THE PRINT EDITION

Prefaces	xvii	25 Data Transmission and Signals26 Communications	588 600
Section 1 Electrical Principles	1	27 Fibreoptics	613
1 International System of Measurement	3	Section 3 Power Engineering	623
2 Introduction to Electrical Systems	12		
3 Simple DC Circuits	30	28 Multiphase Systems	625
4 Network Theorems	61	29 Transformers	646
5 Capacitance and Capacitors	96	30 Introduction to Machine Theory	680
6 Electromagnetism	136	31 AC Synchronous Machine Windings	702
7 Simple Magnetic Circuits	151	32 Characteristics of AC Synchronous	
8 Inductance in a DC Circuit	166	Machines	715
9 Alternating Voltage and Current	201	33 Induction Motors	72e
10 Single-phase Series Circuits	226	34 Electrical Energy Systems	757
11 Single-phase Parallel Networks	247	35 Power Systems	806
12 Complex Notation	263	36 Direct-current Machines	840
13 Power in AC Circuits	285	37 Direct-current Motors	854
14 Resonance in AC Circuits	302	38 Control System Motors	871
15 Network Theorems Applied to AC Networks	325	39 Motor Selection and Efficiency	880
		40 Power Electronics	899
Section 2 Electronic Engineering	353		
		Section 4 Measurements, Sensing	047
16 Electronic Systems	355	and Actuation	917
17 Passive Filters	362		
18 Amplifier Equivalent Networks	399	41 Control Systems, Sensors and	
19 Semiconductor Materials	419	Actuators	919
20 Rectifiers and Amplifier Circuits	431	42 Electronic Measuring Instruments and Devices	935
21 Interfacing Digital and Analogue Systems	498		
22 Digital Numbers	516	Appendix: Symbols, Abbreviations, Definitions	
23 Digital Systems	531	and Diagrammatic Symbols	957
24 Signals	569	Answers to Exercises	962
		Index	972





	faces	xvii	3.3 3.4	Series circuits versus parallel networks Kirchhoff's laws	41 42
Se	ction 1 Electrical Principles	1	3.5 3.6	Power and energy Resistivity	49 52
1	International System of Measurement	3	3.7 3.8	Temperature coefficient of resistance Temperature rise	54 56
1.1 1.2 1.3	The International System SI derived units Unit of turning moment or torque	4 5 6		Summary of important formulae Terms and concepts	57 58
1.4 1.5	Unit of work or energy Unit of power	7 8	4	Network Theorems	61
1.6 1.7	1.6 Efficiency	9 10 10 11	4.1 New circuit analysis techniques 4.2 Kirchhoff's laws and network solution 4.3 Mesh analysis 4.4 Nodal analysis	Kirchhoff's laws and network solution Mesh analysis	62 62 70 72 75
2	Introduction to Electrical Systems	12	4.6 4.7	Thévenin's theorem The constant-current generator	77 81
2.1 2.2 2.3 2.4 2.5 2.6 2.7	Electricity and the engineer An electrical system Electric charge Movement of electrons Current flow in a circuit Electromotive force and potential difference Electrical units	13 13 15 15 16 16 16	4.11	Norton's theorem Delta–star transformation Star–delta transformation I and T networks Maximum power transfer Summary of important formulae Terms and concepts	84 86 87 88 92 93
2.8 2.9 2.10	Ohm's law Resistors Resistor coding	20 22 23	5	Capacitance and Capacitors	96
2.1	Conductors and insulators The electric circuit in practice Summary of important formulae Terms and concepts	25 26 27 28	5.1 Capacitors5.2 Hydraulic analogy5.3 Charge and voltage5.4 Capacitance5.5 Capacitors in paralle	Hydraulic analogy Charge and voltage Capacitance Capacitors in parallel	97 98 99 99 100
3	Simple DC Circuits	30	5.6 5.7	Capacitors in series Distribution of voltage across capacitors in series	100 101
3.1 3.2	Series circuits Parallel networks	31 36	5.8 5.9 5.10	Capacitance and the capacitor Electric fields Electric field strength and electric flux density	102 103 103

viii CONTENTS

5.12	Relative permittivity Capacitance of a multi-plate capacitor	105 106	8	Inductance in a DC Circuit	166
	Composite-dielectric capacitors	107	8.1	Inductive and non-inductive circuits	167
	Charging and discharging currents	110 111	8.2	Unit of inductance	168
	Growth and decay	111	8.3	Inductance in terms of flux-linkages	100
	Analysis of growth and decay Discharge of a capacitor through a resistor	116	0.5	per ampere	170
	Transients in <i>CR</i> networks	118	8.4	Factors determining the inductance of a coil	173
	Energy stored in a charged capacitor	123	8.5	Ferromagnetic-cored inductor in a	170
	Force of attraction between oppositely	123		d.c. circuit	175
3.20	charged plates	124	8.6	Growth in an inductive circuit	176
5.21	Dielectric strength	125	8.7	Analysis of growth	179
	Leakage and conduction currents in capacitors	126	8.8	Analysis of decay	181
	Displacement current in a dielectric	127	8.9	Transients in LR networks	183
5.24	Types of capacitor and capacitance	127	8.10	Energy stored in an inductor	186
	Summary of important formulae	130		Mutual inductance	189
	Terms and concepts	131		Coupling coefficient	192
				Coils connected in series	193
			8.14	Types of inductor and inductance	195
6	Electromagnetism	136		Summary of important formulae Terms and concepts	196 197
6.1	Magnetic field	137			
6.2	Direction of magnetic field	137			
6.3	Characteristics of lines of magnetic flux	137	9 /	Alternating Voltage and Current	201
6.4	Magnetic field due to an electric current	138			
6.5	Magnetic field of a solenoid	139	9.1	Alternating systems	202
6.6	Force on a current-carrying conductor	140	9.2	Generation of an alternating e.m.f.	202
6.7	Force determination	142	9.3	Waveform terms and definitions	206
6.8	Electromagnetic induction	144	9.4	Relationship between frequency,	
6.9	Direction of induced e.m.f.	144		speed and number of pole pairs	208
	Magnitude of the generated or induced e.m.f.	145	9.5	Average and r.m.s. values of an alternating	
6.11	Magnitude of e.m.f. induced in a coil	147		current	208
	Summary of important formulae	149	9.6	Average and r.m.s. values of sinusoidal	210
	Terms and concepts	149	0.7	currents and voltages	210
			9.7	Average and r.m.s. values of non-sinusoidal	215
			9.8	currents and voltages Representation of an alternating quantity	215
7	Simple Magnetic Circuits	151	9.0	by a phasor	216
			9.9	Addition and subtraction of sinusoidal	210
7.1	Introduction to magnetic circuits	152	2.2	alternating quantities	218
7.2	Magnetomotive force and magnetic		9 10	Phasor diagrams drawn with r.m.s. values	210
	field strength	152	,,10	instead of maximum values	220
7.3	Permeability of free space or magnetic		9.11	Alternating system frequencies in practice	221
	constant	153		Summary of important formulae	222
7.4	Relative permeability	155		Terms and concepts	222
7.5	Reluctance	157		•	
7.6	'Ohm's law for a magnetic circuit'	158			
7.7	Determination of the B/H characteristic	160	10	Single-phase Series Circuits	226
7.8	Comparison of electromagnetic and	1/2			
	electrostatic terms	162	10.1	Pagia a a giranita	225
	Summary of important formulae	163	10.1	Basic a.c. circuits Alternating current in a resistive circuit	227 227
	Terms and concepts	163	10.2	Alternating current in a resistive circuit	221

CONTENTS ix

	Alternating current in an inductive circuit Current and voltage in an inductive circuit Mechanical analogy of an inductive circuit Resistance and inductance in series Alternating current in a capacitive circuit Current and voltage in a capacitive circuit Analogies of a capacitance in an a.c. circuit Resistance and capacitance in series Alternating current in an <i>RLC</i> circuit Summary of important formulae	228 230 232 233 236 237 238 238 240 244	13.11	The practical importance of power factor Power factor improvement or correction Parallel loads Measurement of power in a single-phase circuit Summary of important formulae Terms and concepts Resonance in AC Circuits	296 297 298 300 300 301
11	Terms and concepts Single-phase Parallel Networks	245 247	14.1 14.2 14.3	Introduction Frequency variation in a series RLC circuit The resonant frequency of a series RLC circuit	303 303 306
11.1 11.2 11.3 11.4 11.5	Basic a.c. parallel circuits Simple parallel circuits Parallel impedance circuits Polar impedances Polar admittances Summary of important formulae Terms and concepts	248 248 252 256 259 261 261	14.11 14.12	The current in a series <i>RLC</i> circuit Voltages in a series <i>RLC</i> circuit Quality factor <i>Q</i> Oscillation of energy at resonance Mechanical analogy of a resonant circuit Series resonance using complex notation Bandwidth Selectivity Parallel resonance Current magnification	306 306 307 309 310 310 311 313 316 317
12.1 12.2 12.3	Complex Notation The j operator Addition and subtraction of phasors Voltage, current and impedance	264 265 266		Parallel and series equivalents The two-branch parallel resonant circuit Summary of important formulae Terms and concepts	318 319 322 322
12.4 12.5 12.6	Admittance, conductance and susceptance RL series circuit admittance RC series circuit admittance	269 270 270	15	Network Theorems Applied to AC Networks	325
12.7 12.8 12.9 12.10	Parallel admittance Calculation of power using complex notation Power and voltamperes Complex power Summary of important formulae Terms and concepts	271 275 276 277 281 282	15.1 15.2 15.3 15.4 15.5 15.6 15.7 15.8	One stage further Kirchhoff's laws and network solution Nodal analysis (Node Voltage method) Superposition theorem Thévenin's theorem Norton's theorem Star-delta transformation Delta-star transformation	326 326 333 333 335 340 344 345
13	Power in AC Circuits	285	15.9	Maximum power transfer Terms and concepts	347 348
13.1 13.2 13.3 13.4	The impossible power Power in a resistive circuit Power in a purely inductive circuit Power in a purely capacitive circuit	286 286 287 289		tion 2 Electronic Engineering Electronic Systems	353 355
13.5 13.6 13.7	Power in a circuit with resistance and reactance Power factor Active and reactive currents	290 292 294	16.1 16.2	Introduction to systems Electronic systems	356 357

x CONTENTS

16.3 16.4 16.5 16.6	Basic amplifiers Basic attenuators Block diagrams Layout of block diagrams Summary of important formulae Terms and concepts	357 360 360 361 361 361	19.3 19.4 19.5 19.6 19.7	Covalent bonds An n-type semiconductor A p-type semiconductor Junction diode Construction and static characteristics of a junction diode Terms and concepts	421 423 424 425 428 430
17	Passive Filters	362			
17.1	Introduction	363	20	Rectifiers and Amplifier Circuits	431
17.2	Types of filter	363	20.1	Rectifier circuits	432
17.3	Frequency response	365	20.1	Half-wave rectifier	432
17.4	Logarithms	365	20.3	Full-wave rectifier network	435
17.5	Log scales	368	20.4	Bridge rectifier network	437
17.6	The decibel (dB)	369	20.5	Smoothing	439
17.7	The low-pass or lag circuit	372	20.6	Zener diode	442
17.8	The high-pass or lead circuit	376	20.7	Bipolar junction transistor	442
17.9	Passband (or bandpass) filter	379	20.8	Construction of bipolar transistor	444
17.10	Stopband (or bandstop) filters	382	20.9	Common-base and common-emitter circuits	444
17.11	Bode plots	382		Static characteristics for a common-base circuit	445
17.12	2-port Networks	388		Static characteristics for a common-emitter circuit	
	Summary of important formulae	396		Relationship between α and β	447
	Terms and concepts	397		Load line for a transistor	448
				Transistor as an amplifier	449
				Circuit component selection	456
18	Amplifier Equivalent Networks	399		Equivalent circuits of a transistor	457
				Hybrid parameters	461
18.1	Amplifier constant-voltage equivalent			Limitations to the bipolar junction transistor	462
1011	networks	400		Stabilizing voltages supplies	463
18.2	Amplifier constant-current equivalent	100	20.20	Transistor as a switch	467
10.2	networks	402	20.21	Field effect transistor (FET)	467
18.3	Logarithmic units	404		JUGFET	467
18.4	Frequency response	407		IGFET	470
18.5	Feedback	409	20.24	Static characteristics of a FET	472
18.6	Effect of feedback on input and output		20.25	Equivalent circuit of a FET	472
	resistances	413	20.26	The FET as a switch	473
18.7	Effect of feedback on bandwidth	415	20.27	Cascaded amplifiers	474
18.8	Distortion	415	20.28	Integrated circuits	479
2010	Summary of important formulae	416	20.29	Operational amplifiers	480
	Terms and concepts	416		The inverting operational amplifier	481
	r			The summing amplifier	483
			20.32	The non-inverting amplifier	484
				Differential amplifiers	485
19	Semiconductor Materials	419		Common-mode rejection ratio	487
				Summary of important formulae	487
19.1	Introduction	420		Terms and concepts	489
19.2	Atomic structure	420		-	

CONTENTS xi

	Analogue Systems	498 23.15	Combinational and sequential logic circuits Synchronous and asynchronous	551
21.1 21.2 21.3 21.4 21.5 21.6 21.7 21.8 21.9	The need for conversion Digital-to-analogue conversion D/A converter hardware D/A converters in practice R/2R ladder D/A converter Analogue-to-digital conversion Simple comparator A/D converters Converters in action	499 499 23.17 502 23.18 504 23.19 506 507 509 510 512	sequential circuits Basic storage elements Integrated circuit logic gates Programmable logic and hardware description languages Summary of important formulae Terms and concepts	551 552 560 561 565 565
	Terms and concepts	513 24	Signals	569
22	Digital Numbers	24.1 24.2	Classification of signals Representation of a signal by a continuum of impulses	570 576
22.11 22.12 22.13	Introduction Binary numbers Decimal to binary conversion Binary addition Binary subtraction Binary multiplication Binary division Negative binary numbers Signed binary addition Signed binary subtraction Signed binary multiplication Signed binary division The octal system Hexadecimal numbers	329	Impulse response Convolution sum for discrete-time systems Convolution integral for continuous-time systems Deconvolution Relation between impulse response and unit step response Step and impulse responses of discrete-time systems Summary of important formulae Terms and concepts Data Transmission and Signals	578 578 581 582 583 584 585 586
22	Terms and concepts	530 25.1 25.2 25.3	Transmission of information Analogue signals Digital signals	589 589 590
23.1 23.2 23.3 23.4 23.5 23.6 23.7	Introduction to logic Basic logic statements or functions The OR function The AND function The EXCLUSIVE-OR function The NOT function Logic gates	531 25.4 25.5 532 25.6 532 25.7 532 25.8 533 25.9 533 534	Bandwidth Modulation Filters Demodulation Amplifying signals Digital or analogue? Terms and concepts	592 593 595 596 597 598
23.8 23.9	The NOR function The NAND function	535 535	Communications	600
23.10 23.11 23.12	Logic networks Combinational logic Gate standardization Karnaugh maps for simplifying combinational logic	536 537 540 26.2 26.3 26.4	Basic concepts Information theory for source coding Data communication systems Coding for efficient transmission	601 603 605

xii CONTENTS

26.5	Source coding	609	29.6	Phasor diagram for an ideal loaded	
	Summary of important formulae	611		transformer	653
	Terms and concepts	611	29.7	Useful and leakage fluxes in a transformer	655
			29.8	Leakage flux responsible for the inductive	
				reactance of a transformer	657
27	Fibreoptics	613	29.9	Methods of reducing leakage flux	657
			29.10	Equivalent circuit of a transformer	658
27.1	Introduction	614	29.11	Phasor diagram for a transformer on load	659
27.2	Fibre loss	614		Approximate equivalent circuit of a	
27.3	Refraction	615		transformer	660
27.4	Light acceptance	617	29.13	Simplification of the approximate	
27.5	Attenuation	618		equivalent circuit of a transformer	661
27.6	Bandwidth	618	29.14	Voltage regulation of a transformer	662
27.7	Modulation	619		Efficiency of a transformer	666
27.8	Optical fibre systems	620		Condition for maximum efficiency of a	
27.0	Summary of important formulae	621		transformer	667
	Terms and concepts	622	29.17	Open-circuit and short-circuit tests on a	
	Terms and concepts	022		transformer	669
			29.18	Calculation of efficiency from the	
Sec	tion 3 Power Engineering	623		open-circuit and short-circuit tests	670
			29.19	Calculation of the voltage regulation	
00	Balling Control			from the short-circuit test	670
28	Multiphase Systems	625	29.20	Three-phase core-type transformers	672
				Auto-transformers	672
28.1	Disadvantages of the single-phase system	626		Current transformers	673
28.2	Generation of three-phase e.m.f.s	626		Waveform of the magnetizing current of	
28.3	Delta connection of three-phase windings	627		a transformer	674
28.4	Star connection of three-phase windings	628	29.24	Air-cored transformer	675
28.5	Voltages and currents in a star-connected			Summary of important formulae	676
	system	631		Terms and concepts	676
28.6	Voltages and currents in a delta-connected				
	system	632			
28.7	Power in a three-phase system with a		30	Introduction to Machine Theory	680
	balanced load	635	30	incroduction to machine meety	000
28.8	Measurement of active power in a		•		
	three-phase, three-wire system	636	30.1	The role of the electrical machine	681
28.9	Power factor measurement by means		30.2	Conversion process in a machine	681
	of two wattmeters	638	30.3	Methods of analysis of machine performance	683
28.10	Two-phase systems	641	30.4	Magnetic field energy	684
	Summary of important formulae	642	30.5	Simple analysis of force of alignment	685
	Terms and concepts	643	30.6	Energy balance	686
				Division of converted energy and power	689
			30.8	Force of alignment between parallel	
29	Transformers	646	20.0	magnetized surfaces	690
		0.10	30.9	Rotary motion	693
20.1	Torrest and a	(47		Reluctance motor	694
29.1	Introduction	647	30.11	Doubly excited rotating machines	696
29.2	Core factors	647		Summary of important formulae	698
29.3	Principle of action of a transformer	648		Terms and concepts	698
29.4	EMF equation of a transformer	649			
29.5	Phasor diagram for a transformer on no load	651			

CONTENTS **xiii**

31	AC Synchronous Machine Windings	702	33.14 Shaded-pole motors	752
31.1 31.2 31.3 31.4	General arrangement of synchronous machines Types of rotor construction Stator windings Expression for the e.m.f. of a stator winding	703 703 705 708	33.15 Variable speed operation of induction motors Summary of important formulae Terms and concepts	753 754 754
31.5	Production of rotating magnetic flux by three-phase currents	708	34 Flectrical Energy Systems	757
31.6 31.7	Analysis of the resultant flux due to three-phase currents Reversal of direction of rotation of the magnetic flux Summary of important formulae Terms and concepts	710 712 713 713	34.1 Energy units 34.2 Forms of energy 2 34.3 Energy conversion and quality of energy 3 34.4 Demand for electricity and the	758 758 759 762 766 772
32	Characteristics of AC Synchronous Machines	715	34.7 Renewable energy34.8 Distributed/Embedded generation34.9 Demand management	773 797 798
32.1 32.2 32.3	Armature reaction in a three-phase synchronous generator Voltage regulation of a synchronous generator Synchronous impedance	716 717 718	7 Terms and concepts	802 803 804
32.4 32.5	Parallel operation of synchronous generators Three-phase synchronous motor:	721	35 Power Systems	806
32.6	principle of action Advantages and disadvantages of the synchronous motor Terms and concepts	723 723 724	35.1 System representation 35.2 Power system analysis	807 808 809 812 817
33	Induction Motors	726	35.6 Per-unit impedance	818 819
33.1 33.2 33.3 33.4 33.5	Principle of action Frequency of rotor e.m.f. and current The equivalent circuit of the three-phase induction motor Mechanical power and torque The torque/speed curve and effect	727 728 729 735	35.8 Faults in a power system 35.9 Representation of a grid connection 35.10 Transmission Line effects Summary of important formulae Terms and concepts	823 826 827 835 836
33.6	of rotor resistance Experimental tests to obtain motor	739	36 Direct-current Machines	840
33.7 33.8 33.9 33.10	equivalent circuit parameters Starting torque Starting of a three-phase induction motor fitted with a cage rotor Comparison of cage and slip-ring rotors Braking	741 746 747 748 748	36.1 General arrangement of a d.c. machine 36.2 Double-layer drum windings 36.3 Calculation of e.m.f. generated in an armature winding	841 842 845 846
33.11 33.12	Single-phase induction motors Capacitor-run induction motors Split-phase motors	749 751 752	36.5 Armature reaction in a d.c. motor 36.6 Commutation	849 850

xiv CONTENTS

	Summary of important formulae Terms and concepts	852 852	40	Power Electronics	899
	-		40.1 40.2	Introductory Thyristor	900 900
37	Direct-current Motors	854	40.3 40.4	Some thyristor circuits Limitations to thyristor operation	902 904
37.1 37.2 37.3 37.4 37.5 37.6 37.7	Armature and field connections A d.c. machine as generator or motor Speed of a motor Torque of an electric motor Speed characteristics of electric motors Torque characteristics of electric motors Speed control of d.c. motors Summary of important formulae Terms and concepts	855 855 857 858 860 861 862 868	40.5 40.6 40.7 40.8 40.9 40.10 40.11 40.12	The thyristor in practice The fully controlled a.c./d.c. converter AC/DC inversion Switching devices in inverters Three-phase rectifier networks The three-phase fully controlled converter Inverter-fed induction motors Soft-starting induction motors DC to DC conversion switched-mode power supplies Summary of important formulae	90- 902- 905- 908- 909- 911- 911- 912- 913-
38	Control System Motors	871		Terms and concepts	916
38.1 38.2 38.3 38.4 38.5	Review Motors for regulators RPC system requirements Geneva cam The stepping (or stepper) motor	872 872 873 874 874	Sen	tion 4 Measurements, sing and Actuation	917
38.6 38.7	The variable-reluctance motor The hybrid stepping motor	875 876	41	Control Systems, Sensors and Actuators	919
38.8	Drive circuits Terms and concepts	878 879	41.1 41.2 41.3	Introduction Open-loop and closed-loop systems Damping	920 921 922
39	Motor Selection and Efficiency	880	41.4 41.5	Components of a control system Transfer function	924 925
39.1 39.2 39.3 39.4 39.5 39.6 39.7	Selecting a motor Speed Power rating and duty cycles Load torques The motor and its environment Machine efficiency Hysteresis	881 881 882 883 884 885	41.6 41.7 41.8 41.9	Regulators and servomechanisms Types of control Sensors Actuators Terms and concepts	926 928 929 932 933
39.9	Current-ring theory of magnetism Hysteresis loss Losses in motors and generators	886 888 891	42	Electronic Measuring Instruments and Devices	935
39.11 39.12	Efficiency of a d.c. motor Approximate condition for maximum efficiency	893 894	42.1 42.2	Introduction to analogue and electronic instruments Digital electronic voltmeters	936 937
39.13	Determination of efficiency Terms and concepts	894 897	42.3	Digital electronic ammeters and wattmeters	939

CONTENTS xv

42.4	Graphical display devices	939	42.12 Use of the oscilloscope in waveform	
42.5	The vacuum diode	940	measurement	951
42.6	The vacuum triode	941	42.13 Oscilloscope connection	952
42.7	Modern applications of vacuum-tube		Terms and concepts	955
	technology	942		
42.8	Cathode-ray tube	947	Appendix: Symbols, Abbreviations, Definitions	
42.9	Deflecting systems of a cathode-ray tube	948	and Diagrammatic Symbols	957
42.10	Cathode-ray oscilloscope	948	Answers to Exercises	962
42.11	Digital oscilloscope	950	Index	972

Lecturer Resources

For password-protected online resources tailored to support the use of this textbook in teaching, please visit www.pearsoned.co.uk/hughes





There are two main conclusions to be drawn from the Engineering UK 2015 report 'The State of Engineering'. Firstly, that Britain is great at engineering: '...its skilled engineers are world class and engineering makes a vital and valued contribution to the UK economy, and can help mitigate the grand global challenges of climate change, ageing populations, and supply of food, clean water and energy.' Secondly, that the UK, at all levels of education, does not have either the current capacity or the rate of growth needed to meet the forecast demand for skilled engineers by 2022. Engineering accounts for a quarter of UK's turnover according to the report, and that the shortage skills could cost the UK economy up to £27bn a year if companies fail to hire 182,000 engineers annually until 2022. The conclusions are clear. Young people are needed by industry for the exciting jobs that await.

The same report also states: '...that while 12 per cent of parents stated they would like their son to become an engineer, only 2 per cent said the same about their daughter.' By failing to inspire girls, we're cutting ourselves off from an enormous pool of potential talent. Engineering is all about designing and building our future and we need to capture the imagination and attention of the young minds of both sexes, and show them that they can play a part in shaping the world. We hope this edition of Hughes plays its part in educating those electrical and electronic engineers of the future.

This edition represents something of a watershed in the life of *Hughes*. John Hiley is retiring after 15 years as co-author. He writes: 'It has been a privilege to have been able to contribute to the continuing success of this textbook, one which has informed my whole career in Electrical and Electronic Engineering. I never stopped learning from it either as a student in the late 1960s (using the 4th edition), as an engineer in industry or latterly as a University Teacher. A new author will, of course, bring different expertise to the continued development of the textbook, and I'm sure that, in tandem with my co-author Keith, with whom it has been a great pleasure to collaborate since the 8th edition, the book will continue to inform long into the future. I wish it well.'

Once again, we acknowledge the support of our families during the course of preparation of this new edition, which is dedicated to them all: Wendy, Robin, Helen; Judy, Ben, Rachel and Megan.

John Hiley Keith Brown Heriot Watt University, Edinburgh February 2016



This volume covers the electrical engineering syllabuses of the Second and Third Year Courses for the Ordinary National Certificate in Electrical Engineering and of the First Year Course leading to a Degree of Engineering.

The rationalized M.K.S. system of units has been used throughout this book. The symbols, abbreviations and nomenclature are in accordance with the recommendations of the British Standards Institution, and, for the convenience of students, the symbols and abbreviations used in this book have been tabulated in the Appendix.

It is impossible to acquire a thorough understanding of electrical principles without working out a large number of numerical problems, and, while doing this, students should make a habit of writing the solutions in an orderly manner, attaching the name of the unit wherever possible. When students tackle problems in examinations or in industry, it is important that they express their solutions in a way that is readily intelligible to others, and this facility can only be acquired by experience. Guidance in this respect is given by the 106 worked examples in the text, and the 670 problems afford ample opportunity for practice.

Most of the questions have been taken from examination papers; and for permission to reproduce these questions I am indebted to the University of London, the East Midland Educational Union, the Northern Counties Technical Examination Council, the Union of Educational Institutions and the Union of Lancashire and Cheshire Institutes.

I wish to express my thanks to Dr F. T. Chapman, C.B.E., M.I.E.E., and Mr E. F. Piper, A.M.I.E.E., for reading the manuscript and making valuable suggestions.

Edward Hughes Hove April 1959 We are grateful to the following for permission to reproduce copyright material:

Figures

Figure 34.2 adapted from GB Seven Year Statement 2007, Chapter 2, figure 2.2, www.nationalgrid.com/uk/sys_07/print.asp?chap=2, National Grid 2011; Figure 34.3 adapted from Forecasting Demand, www.nationalgrid.com/NR/rdonlyres/1C4B1304-4631-8A84-3859FB8B4B38/17136/demand. pdf, National Grid 2011.

Tables

Table 34.9 adapted from REpower Systems AG, http://www.repower.de/fileadmin/download/produkte/RE_PP_5M_uk.pdf

Photographs

788 Science Photo Library Ltd: Martin Bond. Cover image: My Life Graphic/Shutterstock

Section one Electrical Principles

- 1 International System of Measurement
- 2 Introduction to Electrical Systems
- 3 Simple DC Circuits
- 4 Network Theorems
- **5** Capacitance and Capacitors
- 6 Electromagnetism
- **7** Simple Magnetic Circuits
- 8 Inductance in a DC Circuit
- **9** Alternating Voltage and Current
- **10** Single-phase Series Circuits
- **11** Single-phase Parallel Networks
- **12** Complex Notation
- **13** Power in AC Circuits
- **14** Resonance in AC Circuits
- **15** Network Theorems Applied to AC Networks



Objectives Contents When you have studied this chapter, you should 1.1 The International System 4 be familiar with the International System of Measurement 1.2 SI derived units 5 be familiar with a variety of derived SI units 1.3 Unit of turning moment or be aware of the concepts of torque and turning moment torque 6 be capable of analysing simple applications of the given SI units 1.4 Unit of work or have an understanding of work, energy and power energy 7 be capable of analysing simple applications involving work, energy 1.5 Unit of power 8 and power 1.6 Efficiency 9 have an understanding of efficiency and its relevance to energy and 1.7 Temperature 10 **Summary of important** be capable of analysing the efficiency of simple applications

formulae 10

Terms and concepts 11

Electrical technology is a subject which is closely related to the technologies of mechanics, heat, light and sound. For instance, we use electrical motors to drive machines such as cranes, we use electric heaters to keep us warm, we use electric lamp bulbs perhaps to read this book and we use electric radios to listen to our favourite music.

have an understanding of temperature and its units of measurement

At this introductory stage, let us assume that we have some understanding of physics in general and, in particular, let us assume that we have some understanding of the basic mechanics which form part of any study of physics. It is not necessary to have an extensive knowledge, and in this chapter we shall review the significant items of which you should have an understanding. We shall use these to develop an appreciation of electrical technology.

In particular, we shall be looking at the concepts of work, energy and power since the underlying interest that we have in electricity is the delivery of energy to a point of application. Thus we drive an electric train yet the power source is in a generating station many kilometres away, or we listen to a voice on the phone speaking with someone possibly on the other side of the world. It is electricity which delivers the energy to make such things happen.

1.1 The International System

The International System of Units, known as SI in every language, was formally introduced in 1960 and has been accepted by most countries as their only legal system of measurement.

One of the SI's most important advantages over its predecessors is that it is a coherent system wherever possible. A system is coherent if the product or quotient of any two quantities is the unit of the resultant quantity. For example, unit area results when unit length is multiplied by unit length. Similarly, unit velocity results when unit length or distance is divided by unit time.

The SI is based on the measures of six physical quantities:

Mass
Length
Time
Electric current
Absolute temperature
Luminous intensity

All other units are derived units and are related to these base units by definition.

If we attempt to analyse relationships between one unit and another, this can be much more readily achieved by manipulating symbols, e.g. A for areas, W for energy and so on. As each quantity is introduced, its symbol will be highlighted as follows:

Energy Symbol: W

Capital letters are normally used to represent constant quantities – if they vary, the symbols can be made lower case, i.e. W indicates constant energy whereas w indicates a value of energy which is time varying.

The names of the SI units can be abbreviated for convenience. Thus the unit for energy – the joule – can be abbreviated to J. This will be highlighted as follows:

Energy Symbol: W Unit: joule (J)

Here the unit is given the appropriate unit abbreviation in brackets. These are only used after numbers, e.g. 16 J. By comparison, we might refer to a few joules of energy.

Now let us consider the six base quantities.

The *kilogram* is the mass of a platinum-iridium cylinder preserved at the International Bureau of Weights and Measures at Sèvres, near Paris, France.

Mass Symbol: m Unit: kilogram (kg)

It should be noted that the megagram is also known as the tonne (t).

The *metre* is the length equal to 1 650 763.73 wavelengths of the orange line in the spectrum of an internationally specified krypton discharge lamp.

Length Symbol: *l* Unit: metre (m)

Length and distance are effectively the same measurement, but we use the term distance to indicate a length of travel. In such instances, the symbol d may be used instead of l. In the measurement of length, the centimetre is additional to the normal multiple units.

The *second* is the interval occupied by 9 192 631 770 cycles of the radiation corresponding to the transition of the caesium–133 atom.

Time Symbol: t Unit: second (s)

Although the standard submultiples of the second are used, the multiple units are often replaced by minutes (min), hours (h), days (d) and years (a).

The *ampere* is defined in section 2.7.

Electric current Symbol: I Unit: ampere (A)

The *kelvin* is 1/273.16 of the thermodynamic temperature of the triple point of water. On the Celsius scale the temperature of the triple point of water is 0.01 °C, hence

$$0^{\circ}C = 273.15 \text{ K}$$

A temperature interval of 1 $^{\circ}$ C = a temperature interval of 1 K. The *candela* is the unit of luminous intensity.

1.2 SI derived units

Although the physical quantities of area, volume, velocity, acceleration and angular velocity are generally understood, it is worth noting their symbols and units.

Area	Symbol: A	Unit: square metre (m²)
Volume	Symbol: V	Unit: cubic metre (m³)
Velocity	Symbol: <i>u</i>	Unit: metre per second (m/s)
Acceleration	Symbol: a	Unit: metre per second squared (m/s²)

Angular velocity Symbol: ω Unit: radian per second (rad/s)

The unit of force, called the newton, is that force which, when applied to a body having a mass of one kilogram, gives it an acceleration of one metre per second squared.

Force Symbol: F Unit: newton (N)

$$F = ma ag{1.1}$$

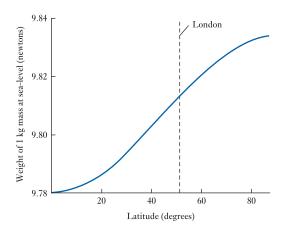
F [newtons] = m [kilograms] $\times a$ [metres per second²]

Weight The weight of a body is the gravitational force exerted by the Earth on that body. Owing to the variation in the radius of the Earth, the gravitational force on a given mass, at sea-level, is different at different latitudes, as shown in Fig. 1.1. It will be seen that the weight of a 1 kg mass at sea-level in the London area is practically 9.81 N. For most purposes we can assume

The weight of a body
$$\approx 9.81m$$
 newtons [1.2]

where *m* is the mass of the body in kilograms.

Fig. 1.1 Variation of weight with latitude



Example 1.1

A force of 50 N is applied to a mass of 200 kg. Calculate the acceleration.

Substituting in expression [1.1], we have

$$50 [N] = 200 [kg] \times a$$

$$\therefore \qquad a = 0.25 \text{ m/s}^2$$

Example 1.2

A steel block has a mass of 80 kg. Calculate the weight of the block at sea-level in the vicinity of London.

Since the weight of a 1 kg mass is approximately 9.81 N,

Weight of the steel block =
$$80 \text{ [kg]} \times 9.81 \text{ [N/kg]}$$

= 785 N

In the above example, it is tempting to give the answer as 784.8 N, but this would be a case of false accuracy. The input information was only given to three figures and therefore the answer should only have three significant numbers, hence 784.8 ought to be shown as 785. Even here, it could be argued that the 80 kg mass was only given as two figures and the answer might therefore have been shown as 780 N. Be careful to show the answer as a reasonable compromise. In the following examples, such adjustments will be brought to your attention.

1.3 Unit of turning moment or torque

If a force F, in newtons, is acting at right angles to a radius r, in metres, from a point, the turning moment or torque about that point is

Fr newton metres

Torque Symbol: T (or M) Unit: newton metre (N m)

If the perpendicular distance from the line of action to the axis of rotation is r, then

$$T = Fr ag{1.3}$$

The symbol M is reserved for the torque of a rotating electrical machine.

1.4 Unit of work or energy

The SI unit of energy is the *joule* (after the English physicist, James P. Joule, 1818–1889). The joule is the work done when a force of 1 N acts through a distance of 1 m in the direction of the force. Hence, if a force F acts through distance l in its own direction

Work done =
$$F[\text{newtons}] \times l[\text{metres}]$$

= $Fl[\text{joules}]$

Work or energy Symbol: W Unit: joule (J)

$$W = Fl ag{1.4}$$

Note that energy is the capacity for doing work. Both energy and work are therefore measured in similar terms.

If a body having mass m, in kilograms, is moving with velocity u, in metres per second

Kinetic energy = $\frac{1}{2} mu^2$ joules

$$\therefore W = \frac{1}{2}mu^2 \tag{1.5}$$

If a body having mass m, in kilograms, is lifted vertically through height h, in metres, and if g is the gravitational acceleration, in metres per second squared, in that region, the potential energy acquired by the body is

Work done in lifting the body = mgh joules

$$W \simeq 9.81mh$$

Example 1.3

A body having a mass of 30 kg is supported 50 m above the Earth's surface. What is its potential energy relative to the ground?

If the body is allowed to fall freely, calculate its kinetic energy just before it touches the ground. Assume gravitational acceleration to be 9.81 m/s².

Weight of body =
$$30 [kg] \times 9.81 [N/kg] = 294.3 N$$

$$\therefore$$
 Potential energy = 294.3 [N] \times 50 [m] = 14 700 J

Note: here we carried a false accuracy in the figure for the weight and rounded the final answer to three figures.

If u is the velocity of the body after it has fallen a distance l with an acceleration g

$$u = \sqrt{(2gl)} = \sqrt{(2 \times 9.81 \times 50)} = 31.32 \,\mathrm{m/s}$$

and

Kinetic energy =
$$\frac{1}{2} \times 30 \, [\text{kg}] \times (31.32)^2 \, [\text{m/s}]^2 = 14700 \, \text{J}$$

Hence the whole of the initial potential energy has been converted into kinetic energy. When the body is finally brought to rest by impact with the ground, practically the whole of this kinetic energy is converted into heat.

1.5 Unit of power

Since power is the rate of doing work, it follows that the SI unit of power is the *joule per second*, or *watt* (after the Scottish engineer James Watt, 1736–1819). In practice, the watt is often found to be inconveniently small and so the *kilowatt* is frequently used.

Power Symbol: P Unit: watt (W)

$$P = \frac{W}{t} = \frac{F \cdot l}{t} = F \cdot \frac{l}{t}$$

$$P = Fu$$
[1.7]

In the case of a rotating electrical machine

$$P = M\omega = \frac{2\pi N_r M}{60} \tag{1.8}$$

where N_r is measured in revolutions per minute.

Rotational speed Symbol: N_r Unit: revolution per minute (r/min)

In the SI, the rotational speed ought to be given in revolutions per second but this often leads to rather small numbers, hence it is convenient to give rotational speed in revolutions per minute. The old abbreviation was rev/min and this is still found to be widely in use.

Rotational speed Symbol: n_r Unit: revolution per second (r/s)

There is another unit of energy which is used commercially: the kilowatt hour (kW h). It represents the work done by working at the rate of one kilowatt for a period of one hour. Once known as the Board of Trade Unit, it is still widely referred to, especially by electricity suppliers, as the unit.

$$1 \text{ kW h} = 1000 \text{ watt hours}$$

= $1000 \times 3600 \text{ watt seconds or joules}$
= $3 600 000 \text{ J} = 3.6 \text{ MJ}$

Example 1.4

A stone block, having a mass of 120 kg, is hauled 100 m in 2 min along a horizontal floor. The coefficient of friction is 0.3. Calculate:

- (a) the horizontal force required;
- (b) the work done;
- (c) the power.
- (a) Weight of stone $\approx 120 \, [\text{kg}] \times 9.81 \, [\text{N/kg}] = 1177.2 \, \text{N}$

$$\therefore$$
 Force required = 0.3 × 1177.2 [N] = 353.16 N = 353 N

(b) Work done =
$$353.16 [N] \times 100 [m] = 35316 J$$

= $35.3 kJ$

(c) Power =
$$\frac{35316 \text{ [J]}}{(2 \times 60) \text{[s]}} = 294 \text{ W}$$

Example 1.5

٠.

An electric motor is developing 10 kW at a speed of 900 r/min. Calculate the torque available at the shaft.

Speed =
$$\frac{900 \, [r/min]}{60 \, [s/min]} = 15 \, r/s$$

Substituting in expression [1.8], we have

$$10\,000\,[\mathrm{W}] = T \times 2\pi \times 15\,[\mathrm{r/s}]$$

 $T = 106\,\mathrm{N}\,\mathrm{m}$

1.6 Efficiency

It should be noted that when a device converts or transforms energy, some of the input energy is consumed to make the device operate. The efficiency of this operation is defined as

Efficiency =
$$\frac{\text{energy output in a given time}}{\text{energy input in the same time}} = \frac{W_{\text{o}}}{W_{\text{in}}}$$

$$= \frac{\text{power output}}{\text{power input}} = \frac{P_{\text{o}}}{P_{\text{in}}}$$

Efficiency Symbol: η Unit: none

$$\therefore \qquad \eta = \frac{P_{\rm o}}{P_{\rm in}} \tag{1.9}$$

Example 1.6

A generating station has a daily output of 280 MW h and uses 500 t (tonnes) of coal in the process. The coal releases 7 MJ/kg when burnt. Calculate the overall efficiency of the station.

Input energy per day is

$$W_{\rm in} = 7 \times 10^6 \times 500 \times 1000$$

= 35.0 × 10¹¹ J

Output energy per day is

$$W_{\rm o} = 280 \text{ MW h}$$

= $280 \times 10^6 \times 3.6 \times 10^3 = 10.1 \times 10^{11} \text{ J}$
 $\eta = \frac{W_{\rm o}}{W_{\rm in}} = \frac{10.1 \times 10^{11}}{35.0 \times 10^{11}} = 0.288$

Example 1.7

A lift of 250 kg mass is raised with a velocity of 5 m/s. If the driving motor has an efficiency of 85 per cent, calculate the input power to the motor.

Weight of lift is

$$F = mg = 250 \times 9.81 = 2452 \text{ N}$$

Output power of motor is

$$P_0 = Fu = 2452 \times 5 = 12260 \text{ W}$$

Input power to motor is

$$P_{\rm in} = \frac{P_{\rm o}}{\eta} = \frac{12\,260}{0.85} = 14\,450\,\text{W} = 14.5\,\text{kW}$$

1.7 Temperature

Some mention is required of temperature measurement, which is in the Celsius scale. Absolute temperature is measured in kelvin, but for most electrical purposes at an introductory stage it is sufficient to measure temperature in degrees Celsius.

It should be remembered that both degrees of temperature represent the same change in temperature – the difference lies in the reference zero.

Temperature Symbol: θ Unit: degree Celsius (°C)

A useful constant to note is that it takes 4185 J to raise the temperature of 1 litre of water through 1 °C.

Example 1.8

An electric heater contains 40 litres of water initially at a mean temperature of 15 °C; 2.5 kW h is supplied to the water by the heater. Assuming no heat losses, what is the final mean temperature of the water?

$$W_{\rm in} = 2.5 \times 3.6 \times 10^6 = 9 \times 10^6 \,\mathrm{J}$$

Energy to raise temperature of 40 litres of water through 1 °C is

$$40 \times 4185 \text{ J}$$

Therefore change in temperature is

$$\Delta\theta = \frac{9 \times 10^6}{40 \times 4185} = 53.8$$
°C
 $\theta_2 = \theta_1 + \Delta\theta = 15 + 53.8 = 68.8$ °C

Summary of important formulae

$F[\text{newtons}] = m[\text{kilograms}] \times a[\text{metres per second squared}]$				
i.e. $F = ma$				
Torque $T = Fr$ (newton metres)	[1.3]			
Work $W = Fl$ (joules)	[1.4]			
Work = Energy				
Kinetic energy $W = \frac{1}{2} mu^2$	[1.5]			
Power $P = Fu$ (watts)	[1.7]			
$= T\omega = M\omega = 2\pi nT$	[1.8]			
Efficiency $\eta = P_{\rm o}/P_{\rm in}$	[1.9]			